

4th year mechatronics systems engineering student at Simon Fraser University. Experienced in designing, prototyping, and testing broad range of engineering applications in impact mechanics, theme park attractions, and robotics.

Work/ Co-op Experience

Robotics Engineer

DaoAI Robotics | 09 – 12/2020

- Test random bin-picking software applications using a structure light camera technology and a 6-axis robot (UR5).
- Calibrated 3D camera in preparation for experiments.
- Assisted in software release by conducting user testing, app encryption, gui translation, and app installer packaging.
- Conducted experiments to measure the trueness, precision, and accuracy for 3D camera performance evaluation.
- 3D printed tools and camera mountings for lab testing.
- Drafted English and Chinese documentation for release.

Mechanical Engineer

Dynamic Attractions | 01 – 05/2020

- Designed various parts and assemblies for rollercoaster's switch-track technology using Autodesk Inventor.
- Applied advanced modeling technique to create a robust assembly layout that only relied on 2D sketches.
- Prepared mechanical drawing packages by drafting bill of materials, project information and revision record.
- Facilitated version control and drawing approval process.

R&D Test Engineer

Shield-X Technology | 05 – 08/2019

- Conducted oblique impact testing to investigate the effect of linear & rotational impact on various type of sports helmet.
- Set up lasers and leveling devices to accurately position the test dummy to its designated impact location.
- Developed five testing methodologies for a newly introduced helmet rating system with high accuracy.
- Classified and interpreted test data to evaluate each helmet's performance using LabVIEW and Excel.

Education

BASc: Mechatronics System Engineering

Simon Fraser University

01/2017 - Present

- CGPA: 3.61 / Dean's Honour Roll
- Minor in Mathematics

School/ Community Involvement

Autopilot Software Lead

Team Guardian

- Lead and managed the autopilot team to develop the latest UAV technologies for competition.
- Built a user-interface for the ground control station to monitor the drone parameters.

UX/UI Researcher

SFU OLC

- Assisted with developing the latest online community website by conducting website review and content porting.
- Contributed to the testing of new features, including user testing, and tracking databases for usability.

Technical Project Experience

Eco-Friendly Robot Competition

Mechanical Design

12/2018 – 02/2019

- Implemented a waste collecting robot to differentiate organic/inorganic materials.

3D Camera Field of View Calculator App

Software Development

09/2019 – 12/2020

- Created a 3D camera FOV calculator for hardware selections & analysis.

Honours & Awards

Ecobot Competition 2nd Place

02/2019

BC Hydro/EGBC Scholarship

12/2018

BC Excellence Award

05/2017

Schulich Leader Nominee

2017

Skillsets

Drafting	MATLAB	Helmet testing
3D Modeling	LabVIEW	Camera design
3D Printing	C++/Python	Robot operation
Version Control	HTML/CSS	Data analysis
Excel	Git	Technical writing